

応用数学 A

積分定理

$$\operatorname{div} F = 0? \neq 0?$$

$$\operatorname{rot} F = 0? \neq 0?$$

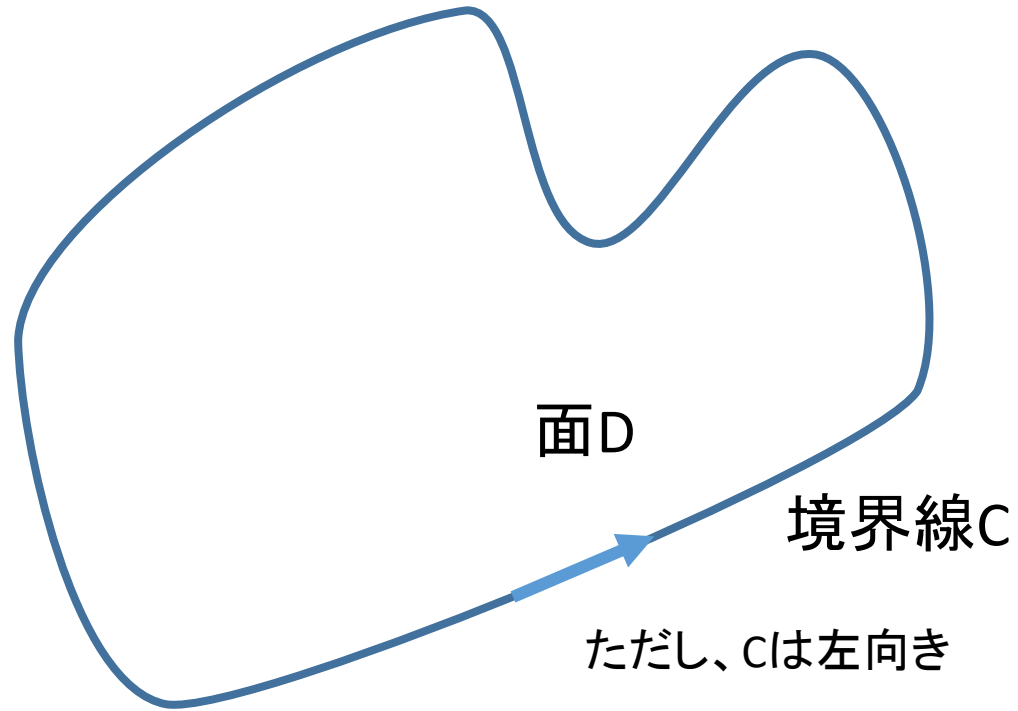
Gaussの定理 $\int \operatorname{div} B dV = \int B \cdot n dS$

Stokesの定理 $\int \nabla \times E \cdot b dS = \int E \cdot dr$

Greenの定理 $\iint_D \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy = \int_C (f dx + g dy) = \int_C (f \vec{e}_i + g \vec{e}_j) \cdot \vec{dr}$

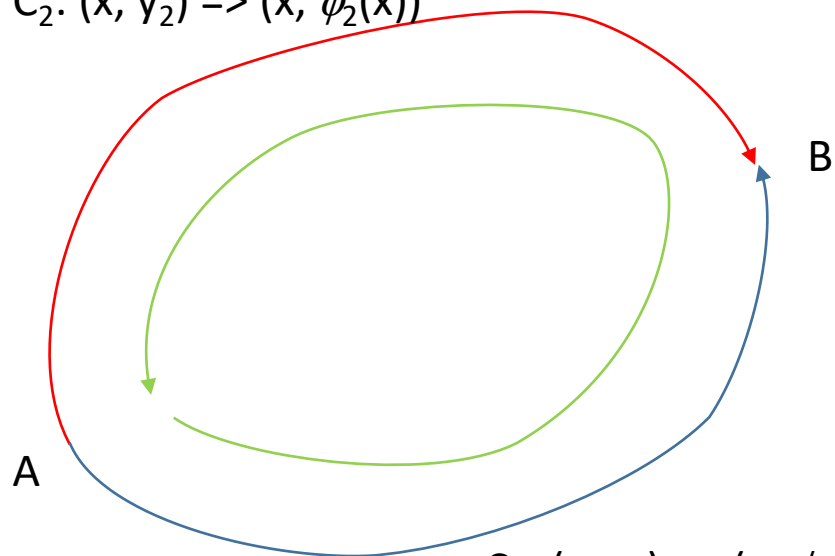
Gaussの発散定理 $\int_S n \times F dS = \int_V \nabla \times F dV$

Green の 定理

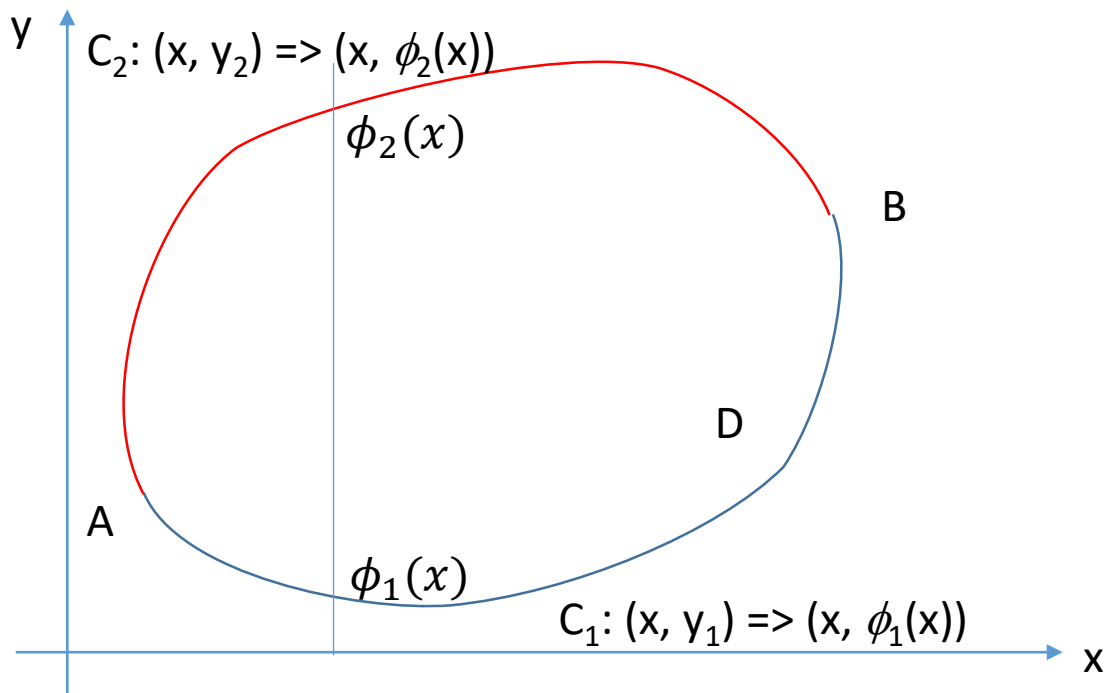


$$\iint_D \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy = \int_C (f dx + g dy) = \int_C (f \vec{e}_i + g \vec{e}_j) \cdot \vec{dr}$$

$$C_2: (x, y_2) \Rightarrow (x, \phi_2(x))$$



$$C_1: (x, y_1) \Rightarrow (x, \phi_1(x))$$



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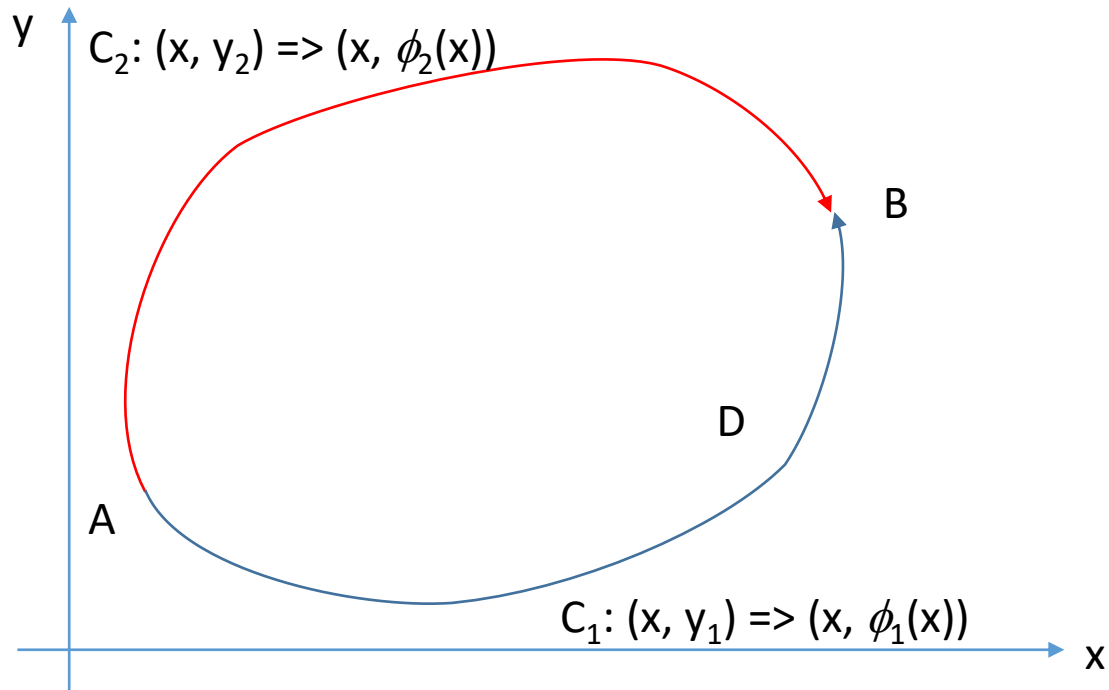
$$\begin{aligned} \int_C f dx &= \int_{C_1-C_2} f dx = \int_{C_1} f dx - \int_{C_2} f dx \\ &= \int_A^B f(x, y_1(x)) dx - \int_A^B f(x, y_2(x)) dx \\ &= \int_A^B f(x, \phi_1(x)) dx - \int_A^B f(x, \phi_2(x)) dx \end{aligned}$$

$$\begin{aligned} \iint_D \left(\frac{\partial f}{\partial y} \right) dx dy &= \int_A^B \left(\int_{\phi_1(x)}^{\phi_2(x)} \frac{\partial f}{\partial y} dy \right) dx = \int_A^B [f]_{\phi_1(x)}^{\phi_2(x)} dx \\ &= \int_A^B (f(x, \phi_2(x)) - f(x, \phi_1(x))) dx \\ &= \int_A^B f(x, \phi_2(x)) dx - \int_A^B f(x, \phi_1(x)) dx \end{aligned}$$

$$\begin{aligned} \int_C f dx &= - \iint_D \left(\frac{\partial f}{\partial y} \right) dx dy \\ \int_C g dy &= - \iint_D \left(\frac{\partial g}{\partial x} \right) dx dy \end{aligned}$$

Greenの定理

$$\int_C f dx + g dy = \iint_D \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy$$



$$\int_C f dx + g dy = \iint_D \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy$$

$$\int_C f dx + g dy = \int_{C_1} f dx + g dy - \int_{C_2} f dx + g dy$$

もし $\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 0$ ならば

$f dx + g dy$ は経路によらずに同じ値をとる。

=>ポテンシャルみたいなもの=> $\Psi(x,y)$

$$\int_{C_1, C_2} f dx + g dy = \Psi(B) - \Psi(A)$$

ここで、 $d\Psi = \frac{\partial \Psi}{\partial x} dx + \frac{\partial \Psi}{\partial y} dy$

$$\Psi(B) - \Psi(A) = \int_A^B d\Psi = \int_A^B \frac{\partial \Psi}{\partial x} dx + \frac{\partial \Psi}{\partial y} dy$$

\downarrow f \downarrow g

$$\operatorname{div} F = 0? \neq 0?$$

Gaussの定理 $\int \operatorname{div} B dV = \int B \cdot n dS$

$$\operatorname{rot} F = 0? \neq 0?$$

Stokesの定理 $\int \nabla \times E \cdot b dS = \int E \cdot dr$

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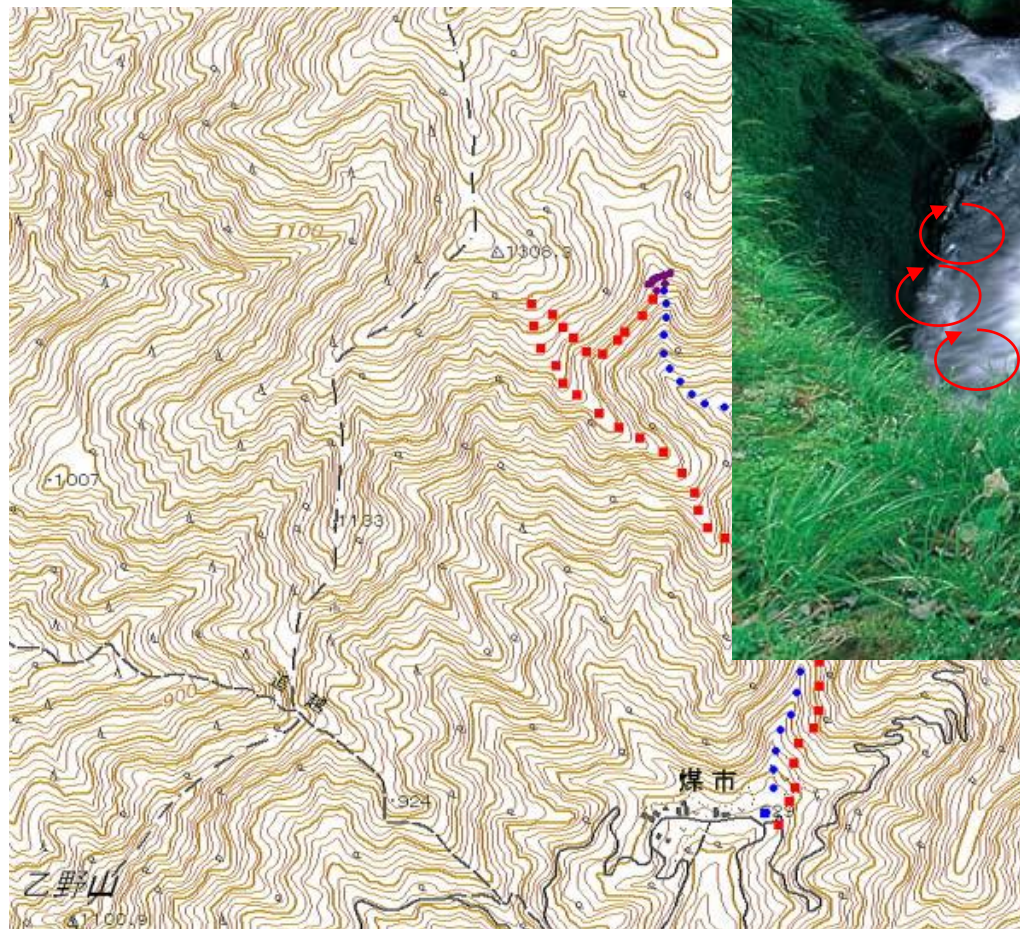
Gaussの発散定理 $\int_S n \times F dS = \int_V \nabla \times F dV$

ベクトル演算

gradient $\nabla\phi$

divergence $\nabla \cdot \phi$

rotation $\nabla \times \phi$



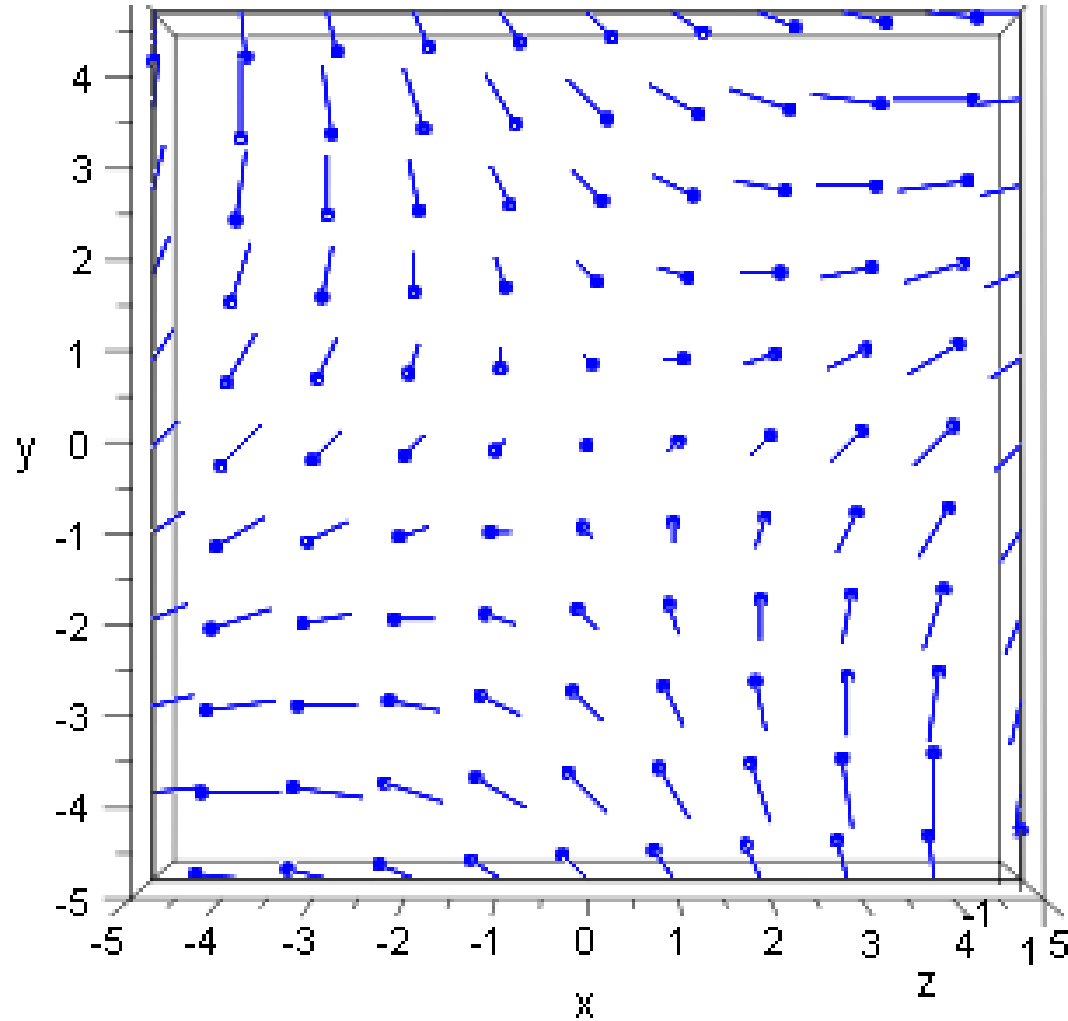
$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$

$$\vec{F} = \begin{pmatrix} fx \\ fy \\ fz \end{pmatrix}$$

$$fx := x + y$$

$$fy = x - y$$

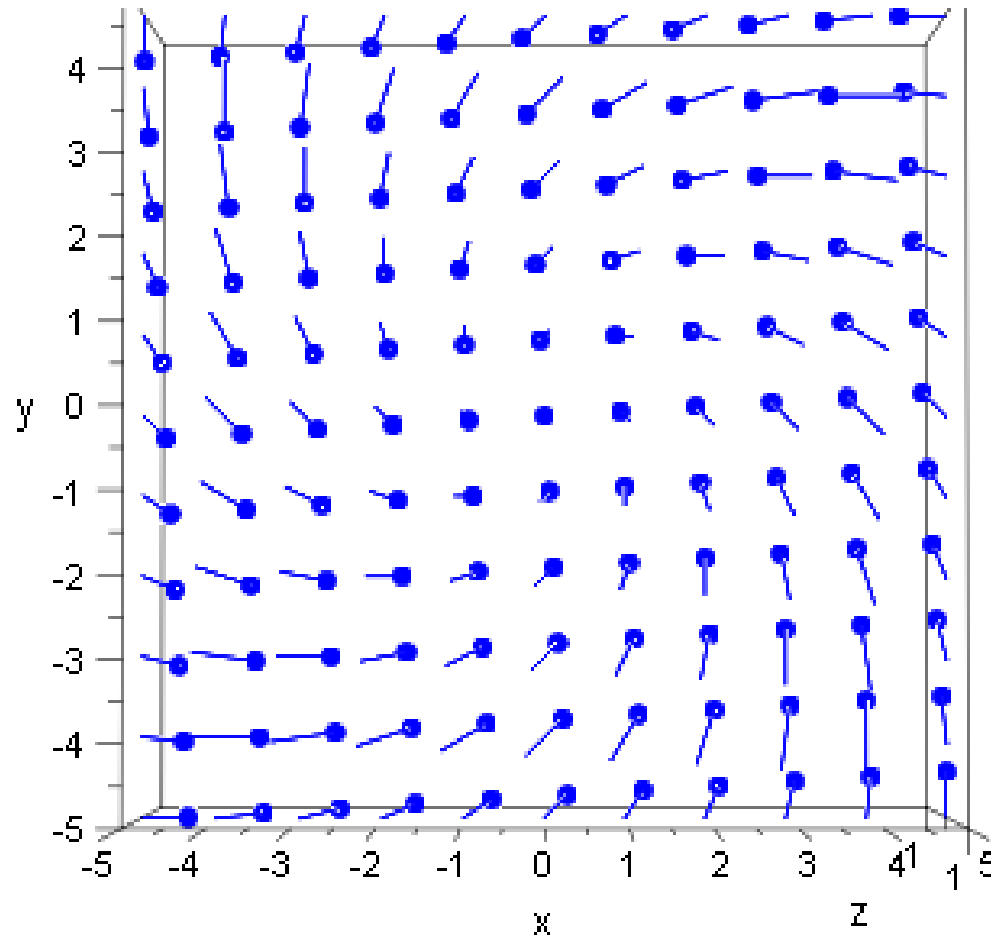
$$fz = 0$$



$$\operatorname{div} F = 0$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\operatorname{div} F = 0? \neq 0? \operatorname{rot} F = 0? \neq 0?$



$$f_x := -x - y$$

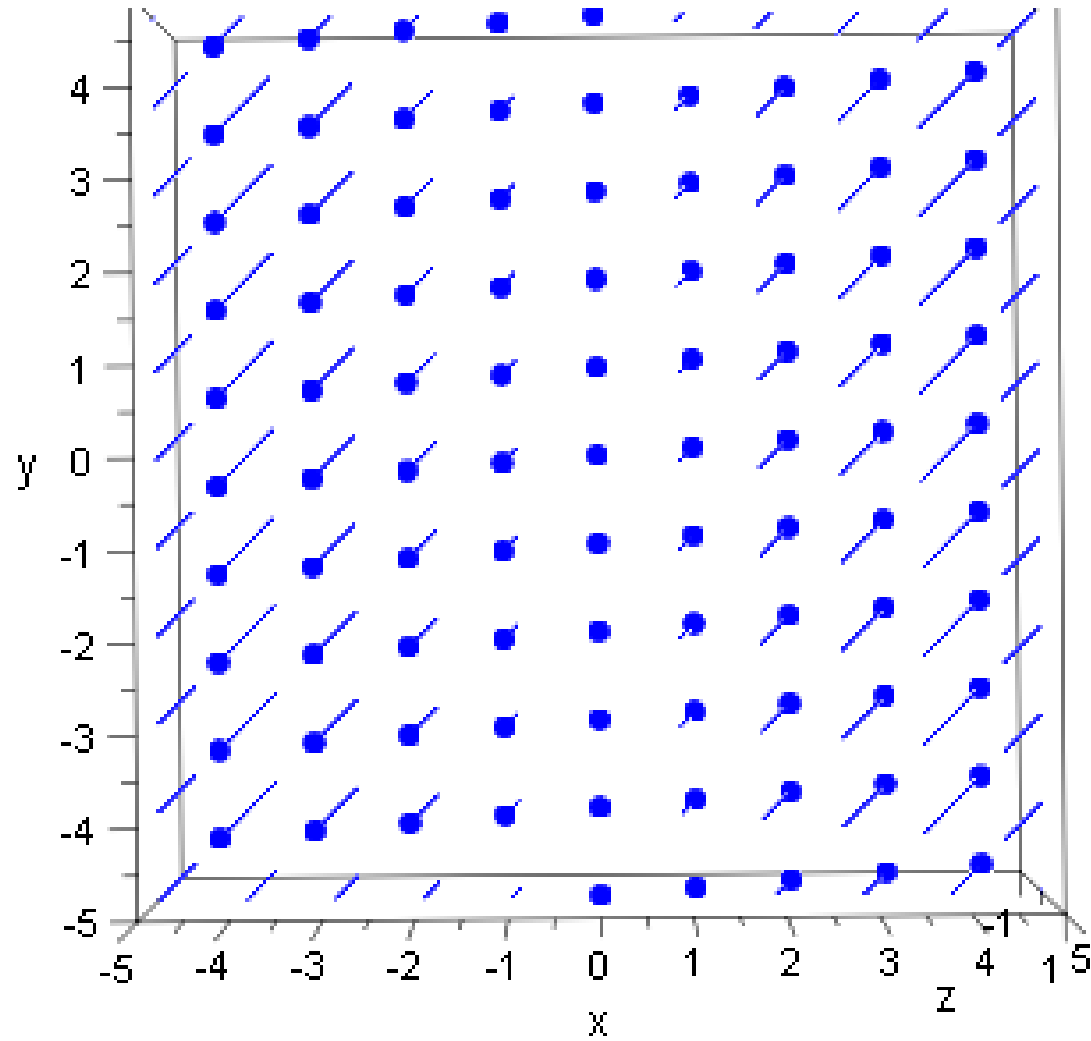
$$f_y = x - y$$

$$f_z = 0$$

$$\operatorname{div} F = -2$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$



$$fx := x$$

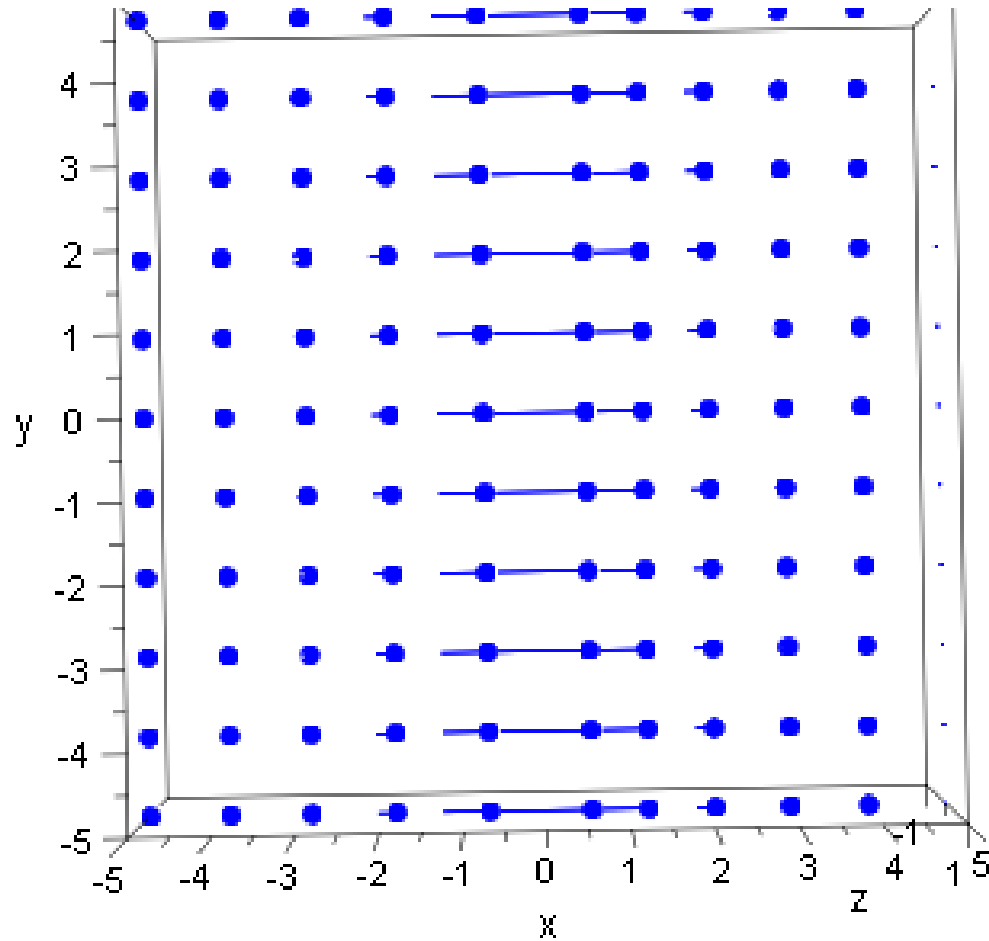
$$fy = x$$

$$fz = 0$$

$$\operatorname{div} F = 1$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$\operatorname{div} F = 0? \neq 0? \operatorname{rot} F = 0? \neq 0?$



$$f_x := \frac{1}{1+x^2}$$

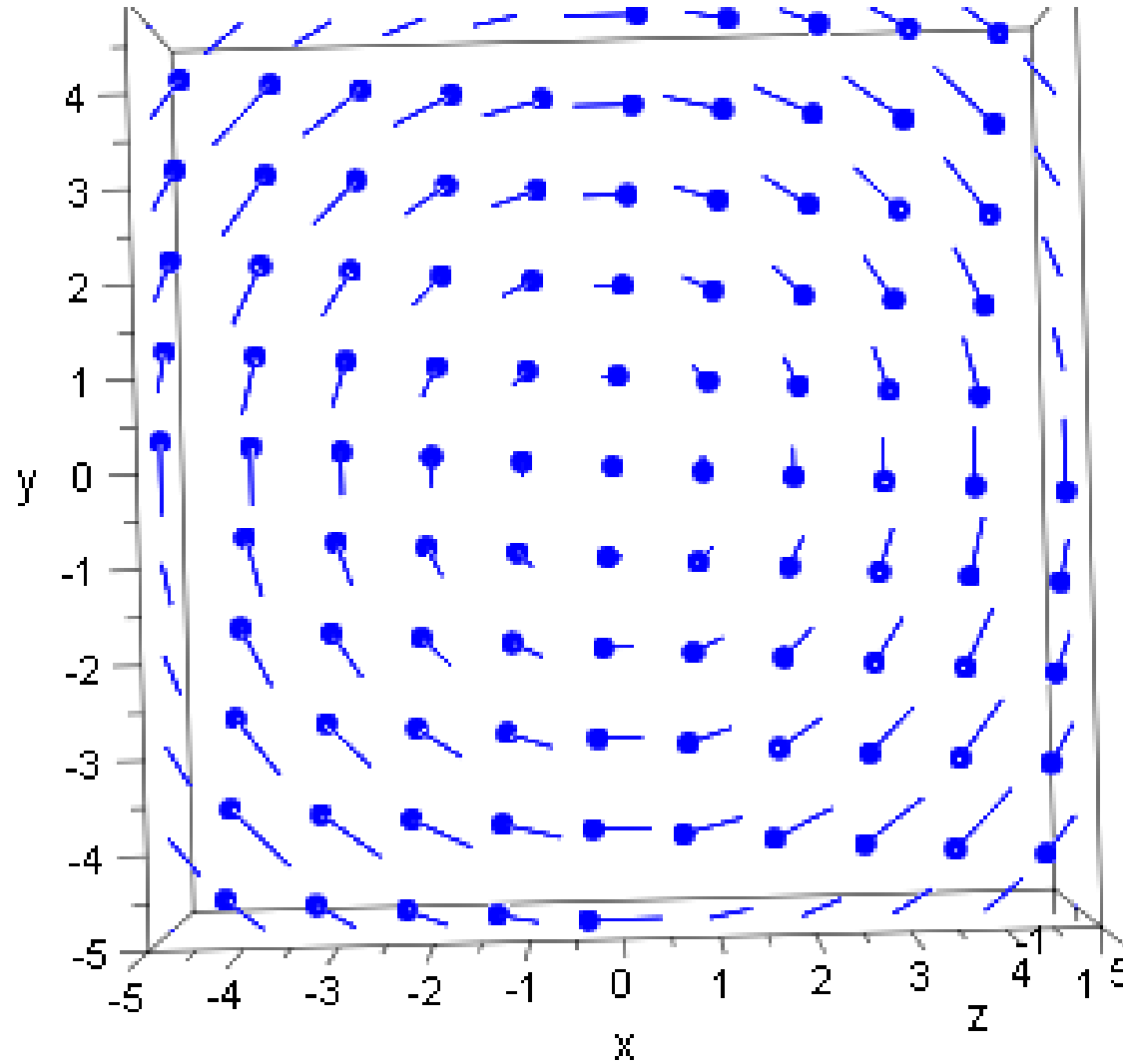
$$f_y = 0$$

$$f_z = 0$$

$$\operatorname{div} F = \frac{-2x}{(1+x^2)^2}$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$

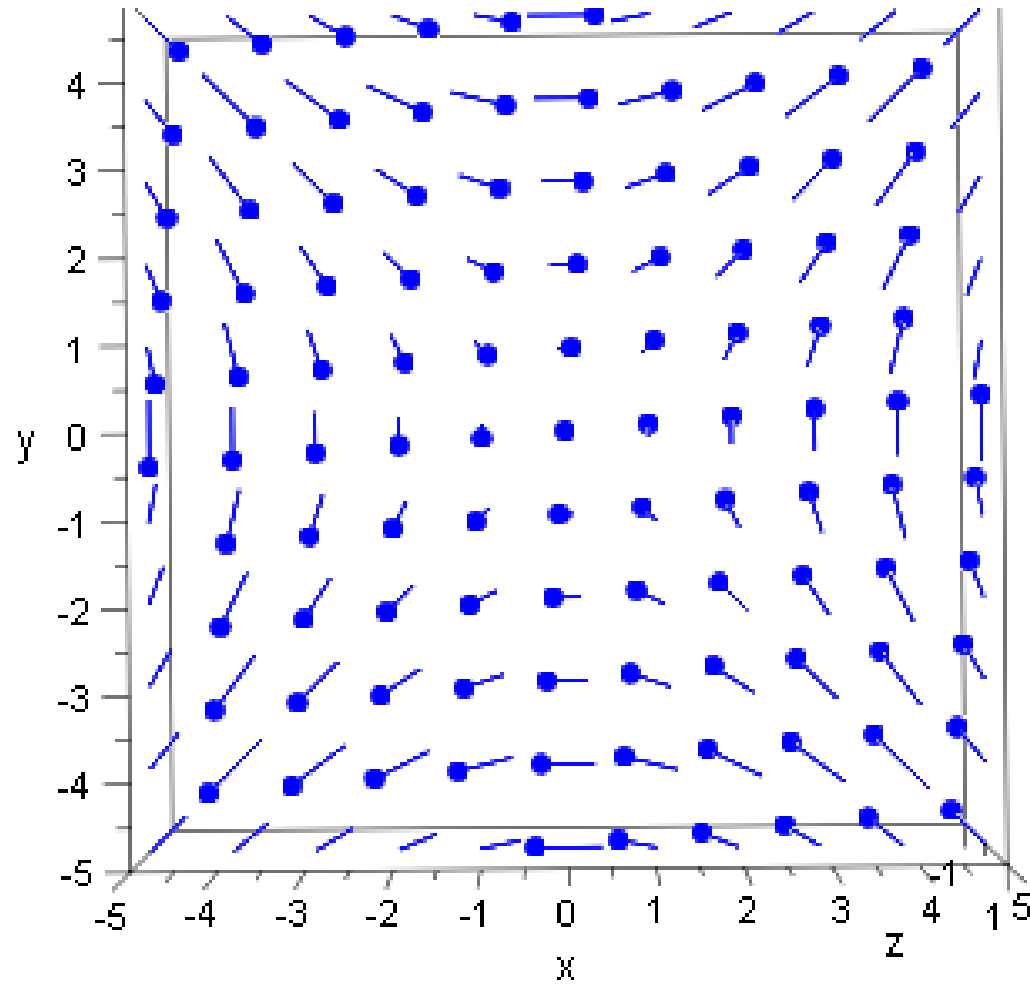


$$\begin{aligned} f_x &:= y \\ f_y &:= -x \\ f_z &:= 0 \end{aligned}$$

$$\operatorname{div} F = 0$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix}$$

$\operatorname{div} F = 0? \neq 0? \operatorname{rot} F = 0? \neq 0?$

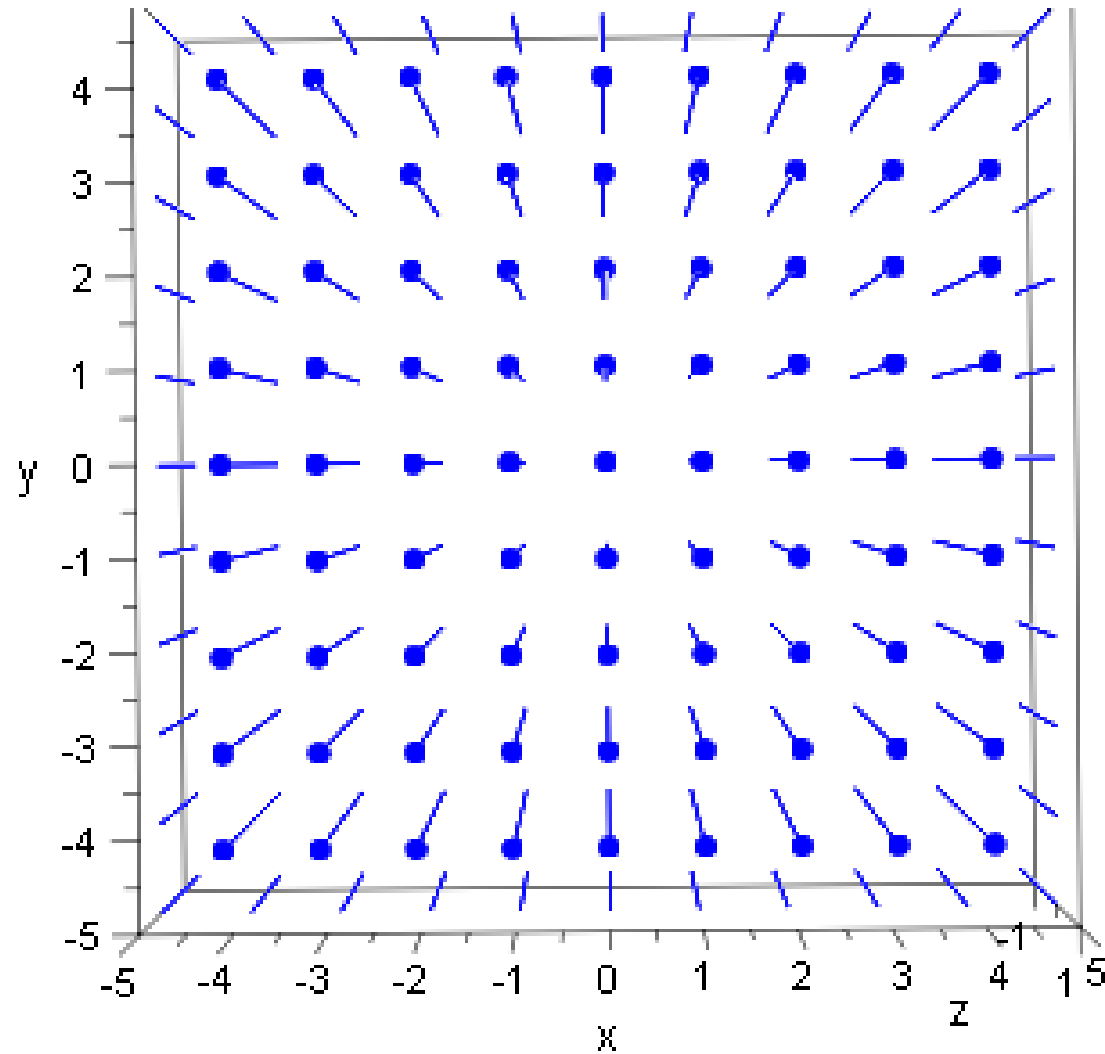


$$\begin{aligned} f_x &:= y \\ f_y &:= x \\ f_z &:= 0 \end{aligned}$$

$$\operatorname{div} F = 0$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$



$$f_x := x$$

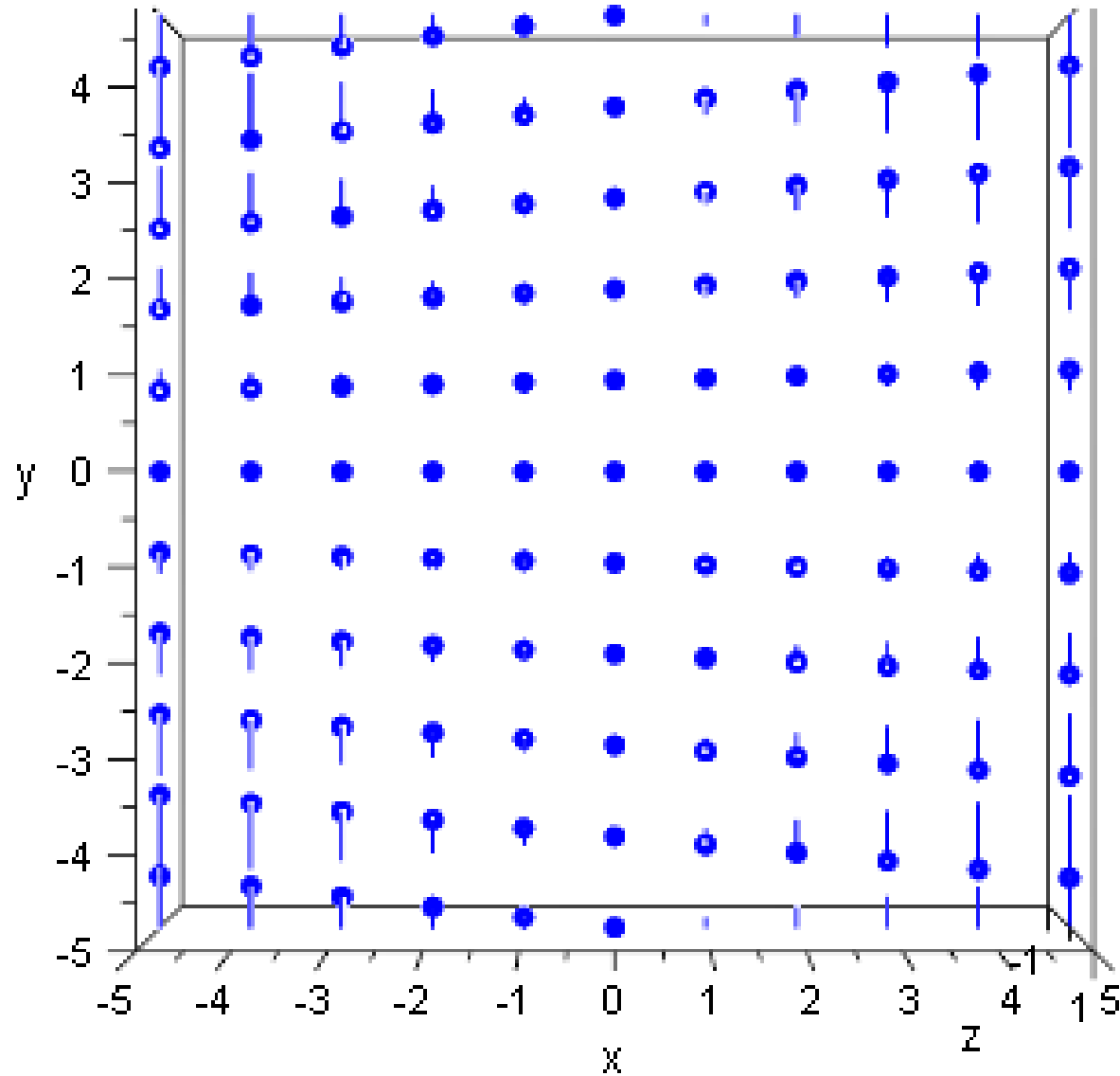
$$f_y := y$$

$$f_z = 0$$

$$\operatorname{div} F = 2$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$

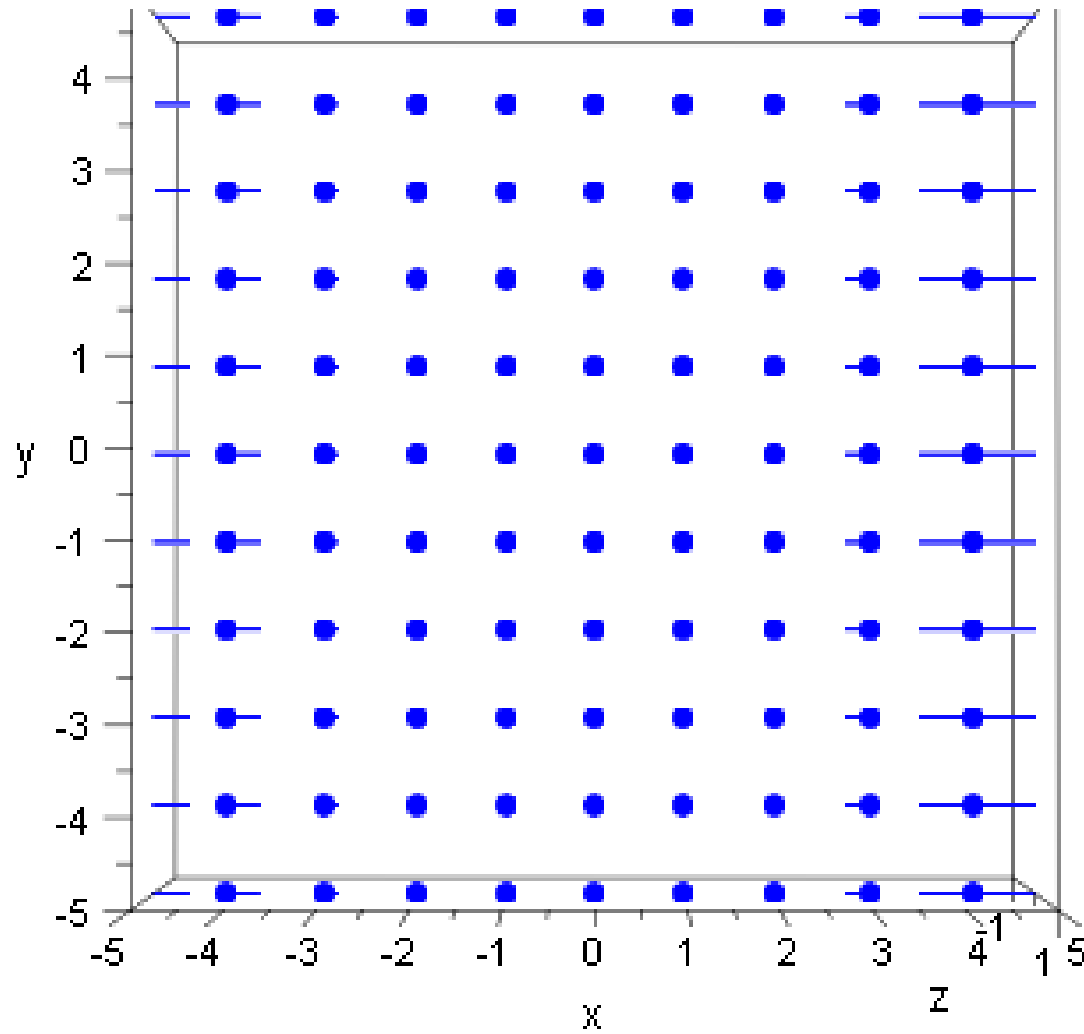


$$\begin{aligned} f_x &:= 0 \\ f_y &:= x * y \\ f_z &:= 0 \end{aligned}$$

$$\operatorname{div} F = x$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ y \end{pmatrix}$$

$\operatorname{div} F = 0?$ $\neq 0?$ $\operatorname{rot} F = 0?$ $\neq 0?$



$$f_x := x^3 + x^2 - 1$$

$$f_y := 0$$

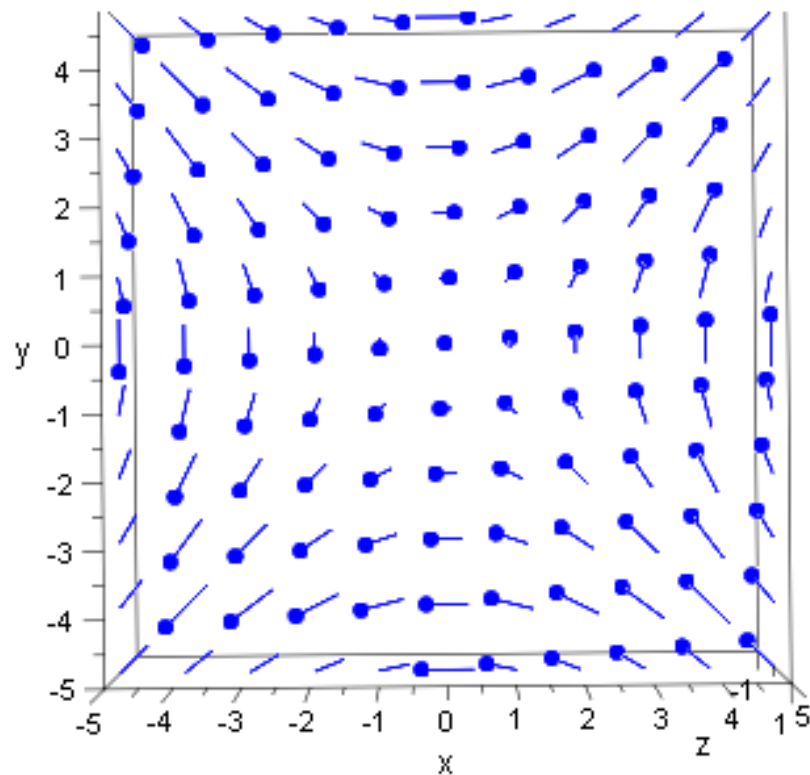
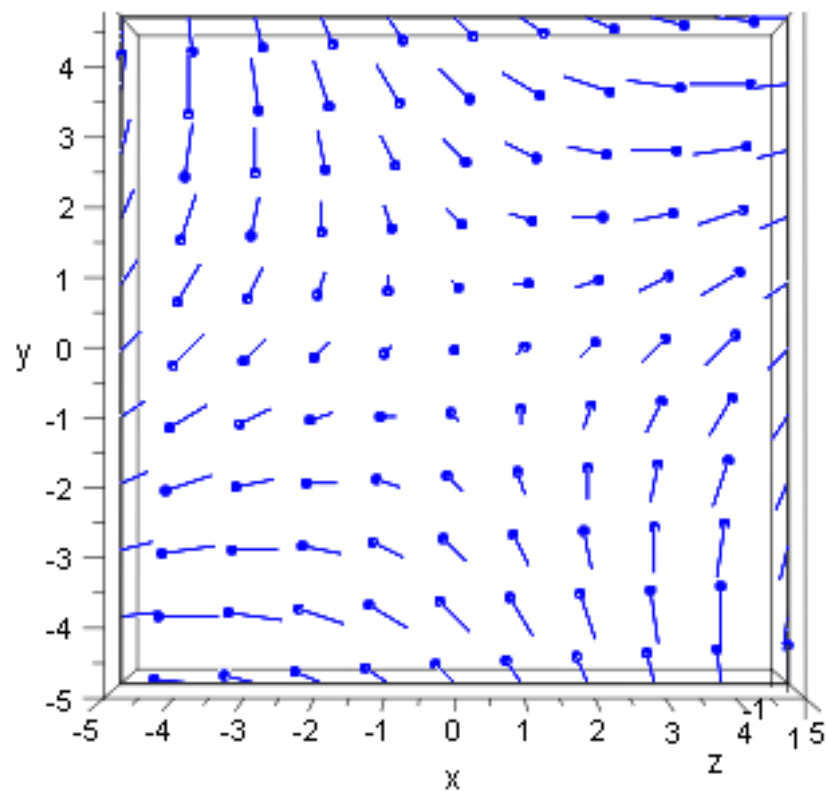
$$f_z := 0$$

$$\operatorname{div} F = 3x^2 + 2x$$

$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\operatorname{div} F = 0$$

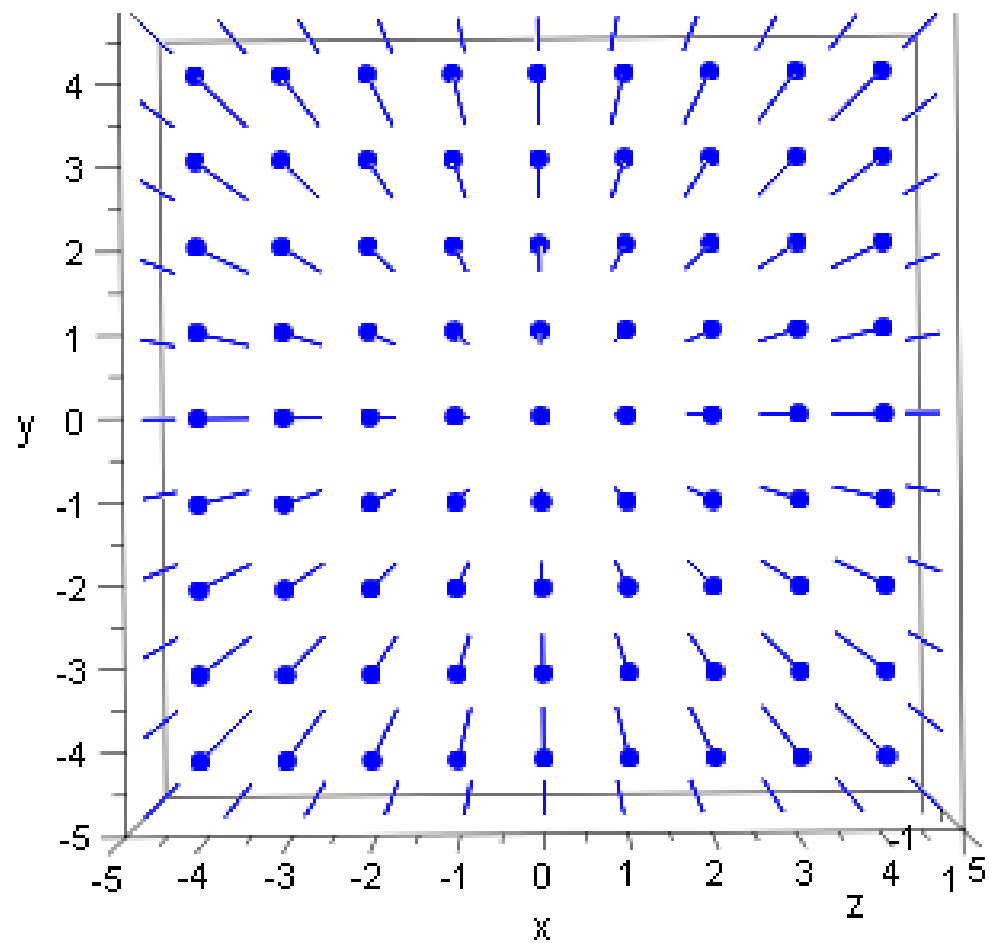
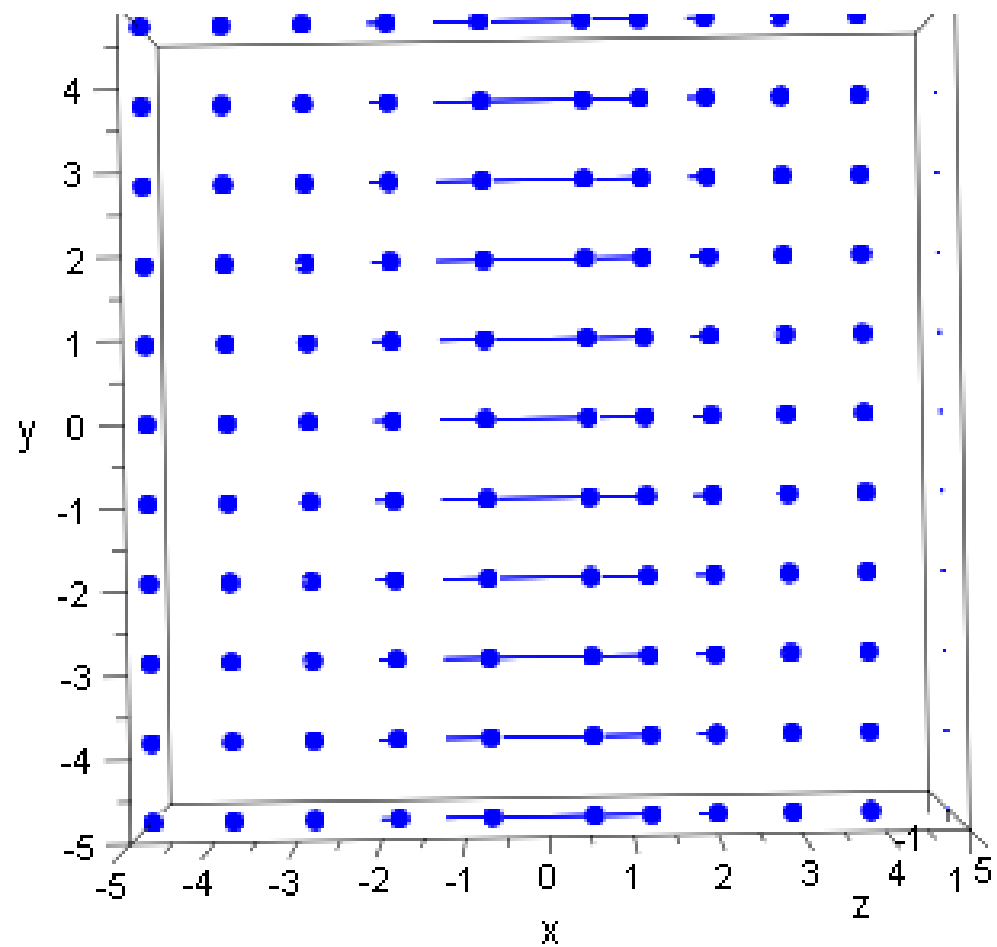
$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$



回転しないし、正味は出入りが無い？

$$\operatorname{div} F \neq 0$$

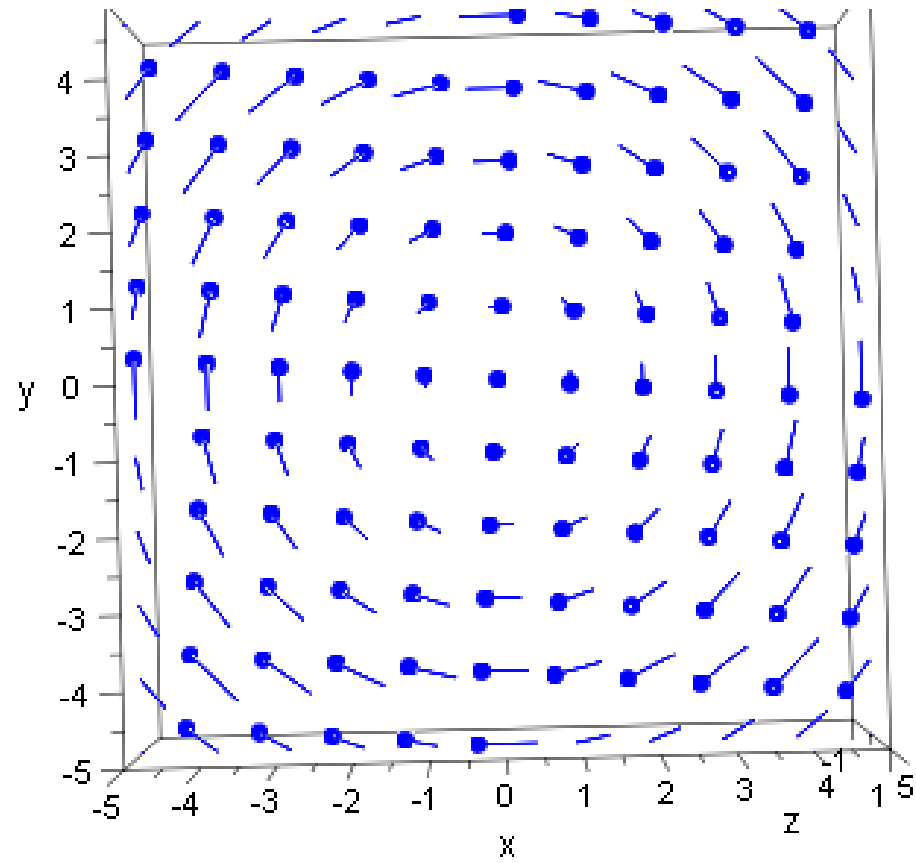
$$\operatorname{rot} F = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$



正味外に出る？

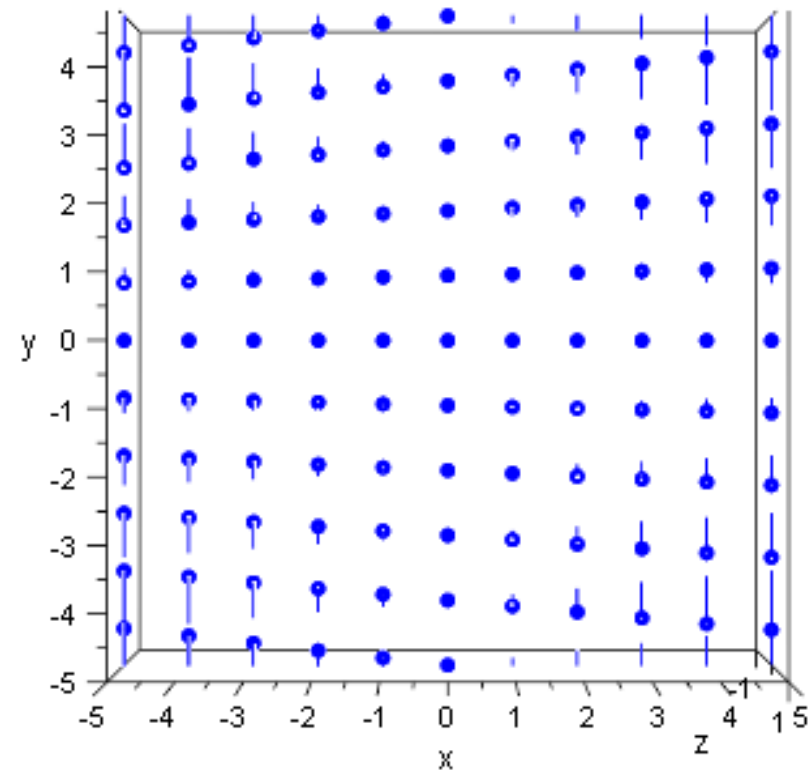
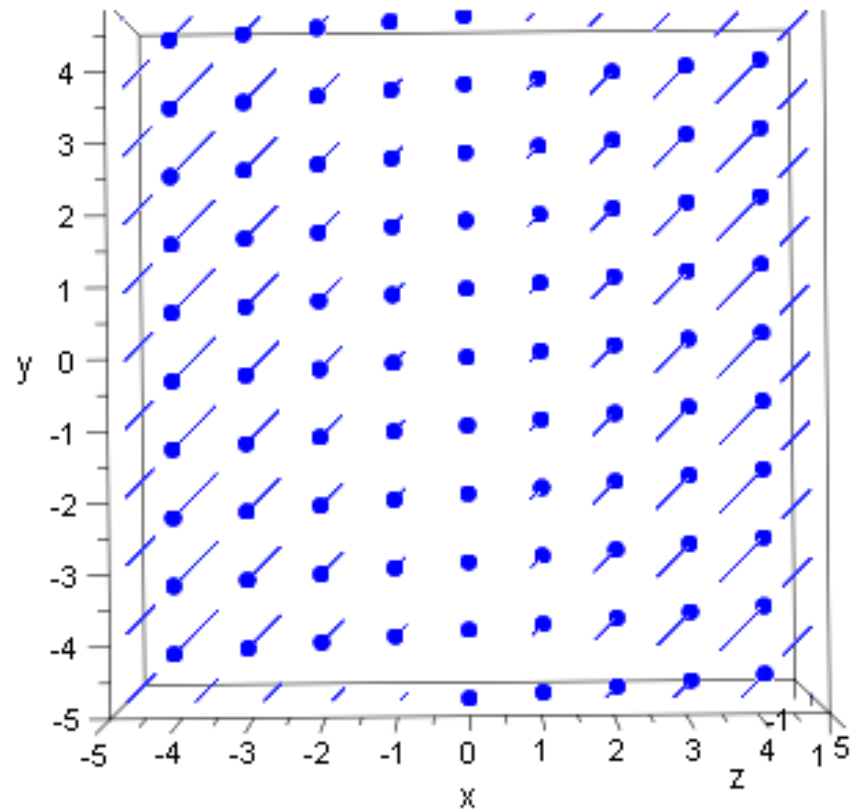
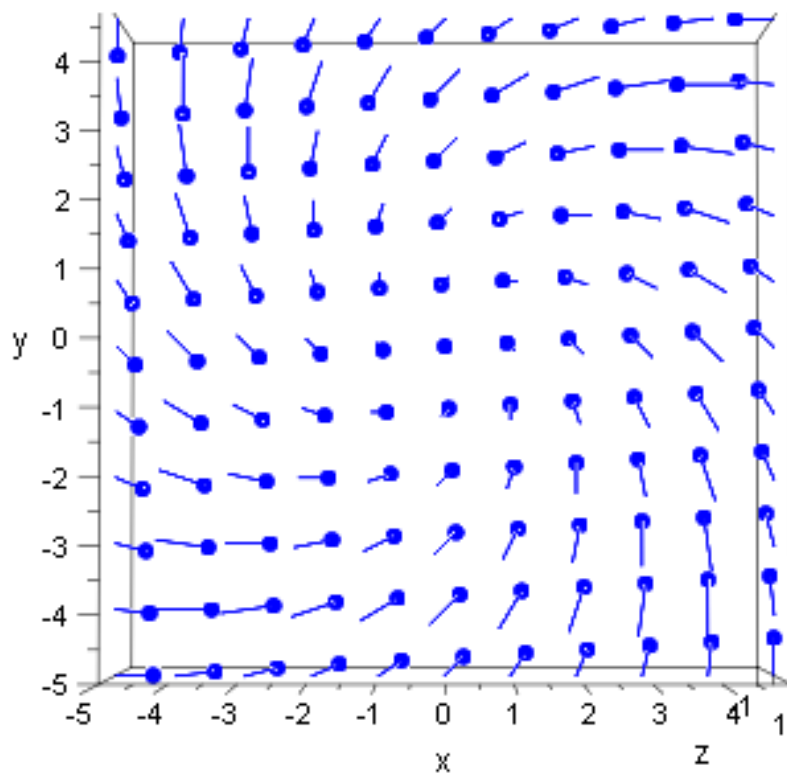
$$\operatorname{div} F = 0$$

$$\operatorname{rot} F \neq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$



回転されてしまう？

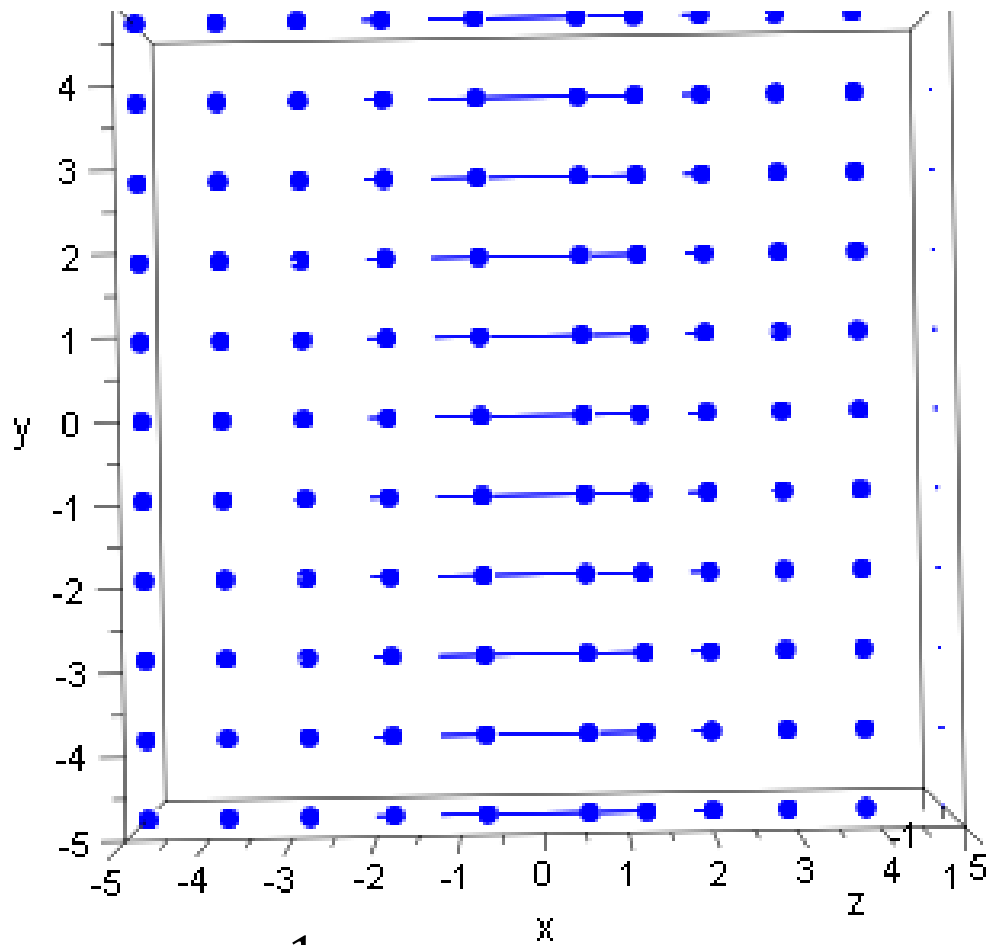
$$\operatorname{div} F \neq 0 \qquad \operatorname{rot} F \neq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$



回転するし、正味の出入りがある？

$$\int_S \mathbf{A} \cdot \mathbf{n} \, dS = \int_V \nabla \cdot \mathbf{A} \, dV$$

ガウスの発散定理

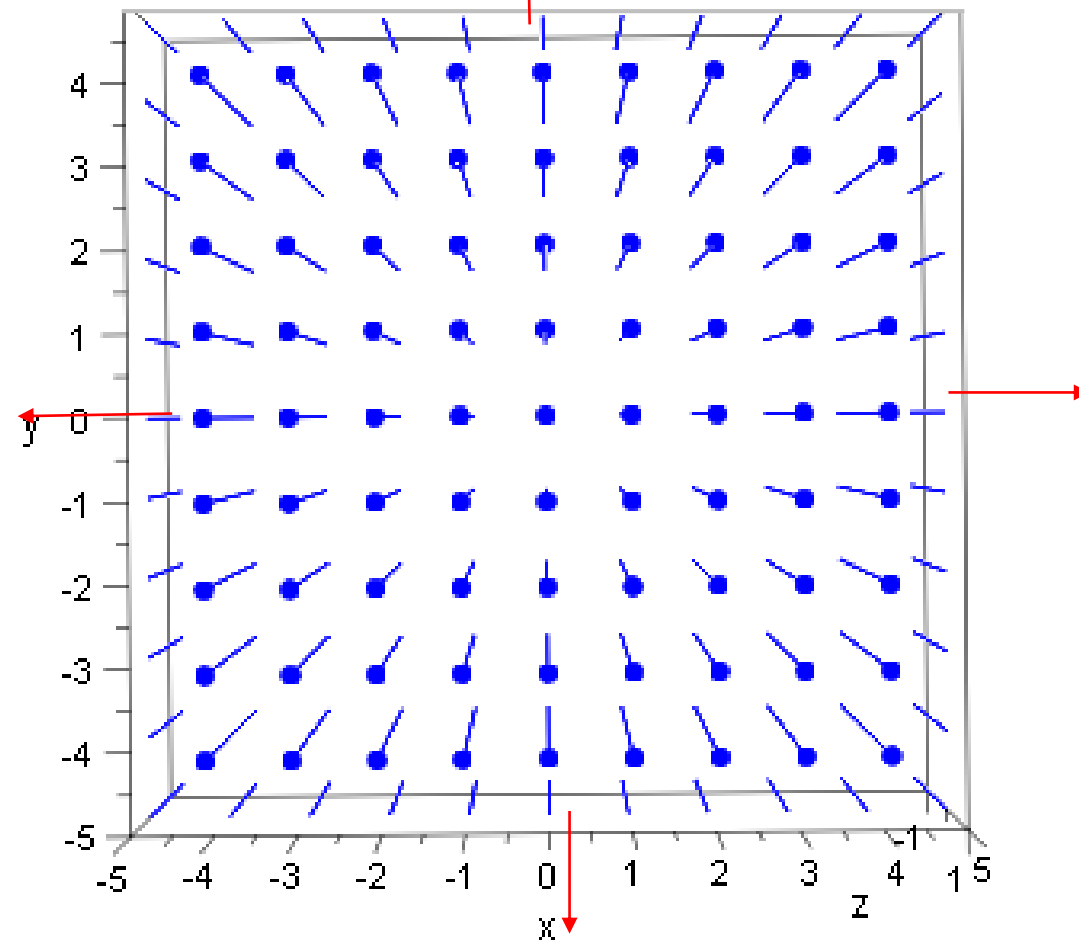


$$f_x = \frac{1}{1+x^2}$$

$$f_y = 0$$

$$f_z = 0$$

$$\operatorname{div} F = \frac{-2x}{(1+x^2)^2}$$



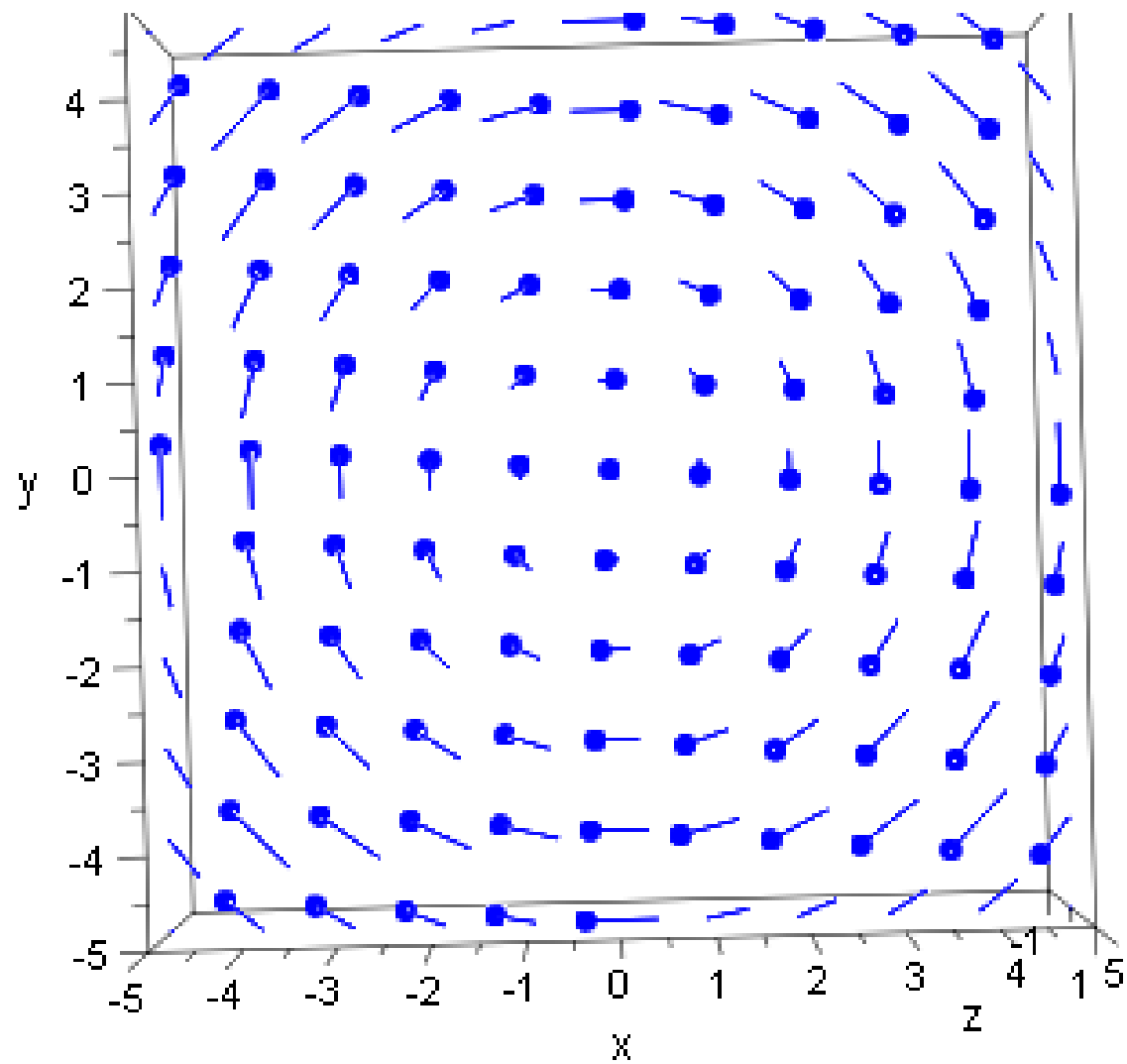
$$f_x := x$$

$$f_y := y$$

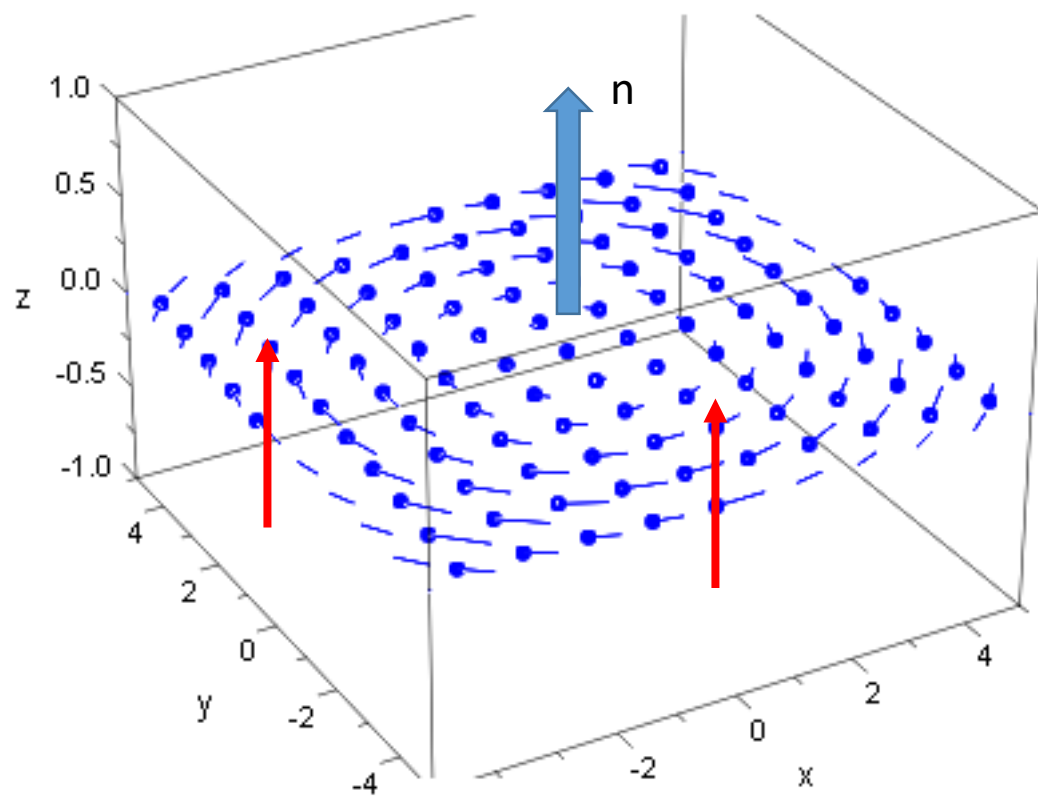
$$f_z = 0$$

$$\int_C \mathbf{A} \cdot d\mathbf{l} = \int_S \nabla \times \mathbf{A} \cdot \mathbf{n} dS$$

ストークスの定理

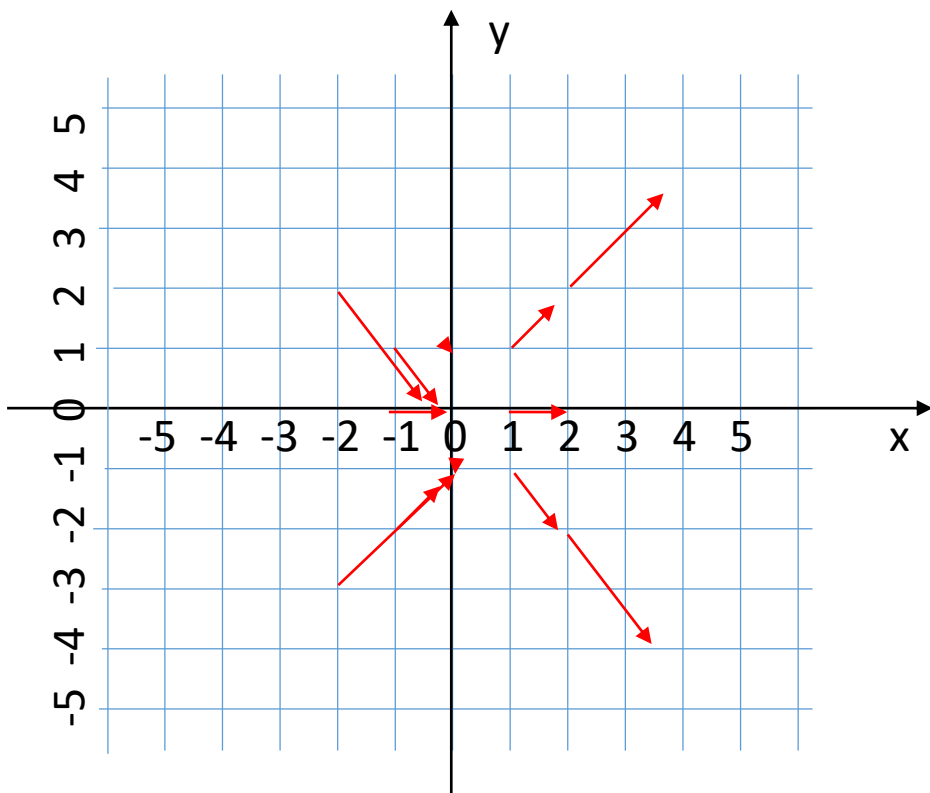


$$\begin{aligned} f_x &:= y \\ f_y &:= -x \\ f_z &:= 0 \end{aligned} \quad \text{rot } F = \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix}$$



確認 問題

$$\operatorname{div} \vec{B} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} B_x \\ B_y \\ B_z \end{pmatrix} \quad \operatorname{rot} \vec{A} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \times \begin{pmatrix} A_x \\ A_y \\ A_z \end{pmatrix} \quad \int_S \vec{F} \cdot \vec{n} dS = \int_V \operatorname{div} \cdot \vec{F} dV$$



$$\vec{F} = \begin{pmatrix} x^2 \\ y^2 \\ 0 \end{pmatrix}$$

$$F = \begin{pmatrix} x^2 \\ xy \\ 0 \end{pmatrix}$$